

# Relativistic Quantum Mechanics

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# Collaborators

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# Motivation

- Scattering experiments at the Thomas Jefferson National Laboratory use high-current electron beams to deduce the structure of baryons, mesons, and light nuclei.

$$c\Delta p\Delta x \geq \hbar c \sim .197(\text{GeV} \cdot \text{fm})$$

$$\Delta x = .2\text{fm} \rightarrow c\Delta p \geq 1\text{GeV} \approx m_p c^2$$

- Relativistic quantum mechanics is needed to interpret these experiments!

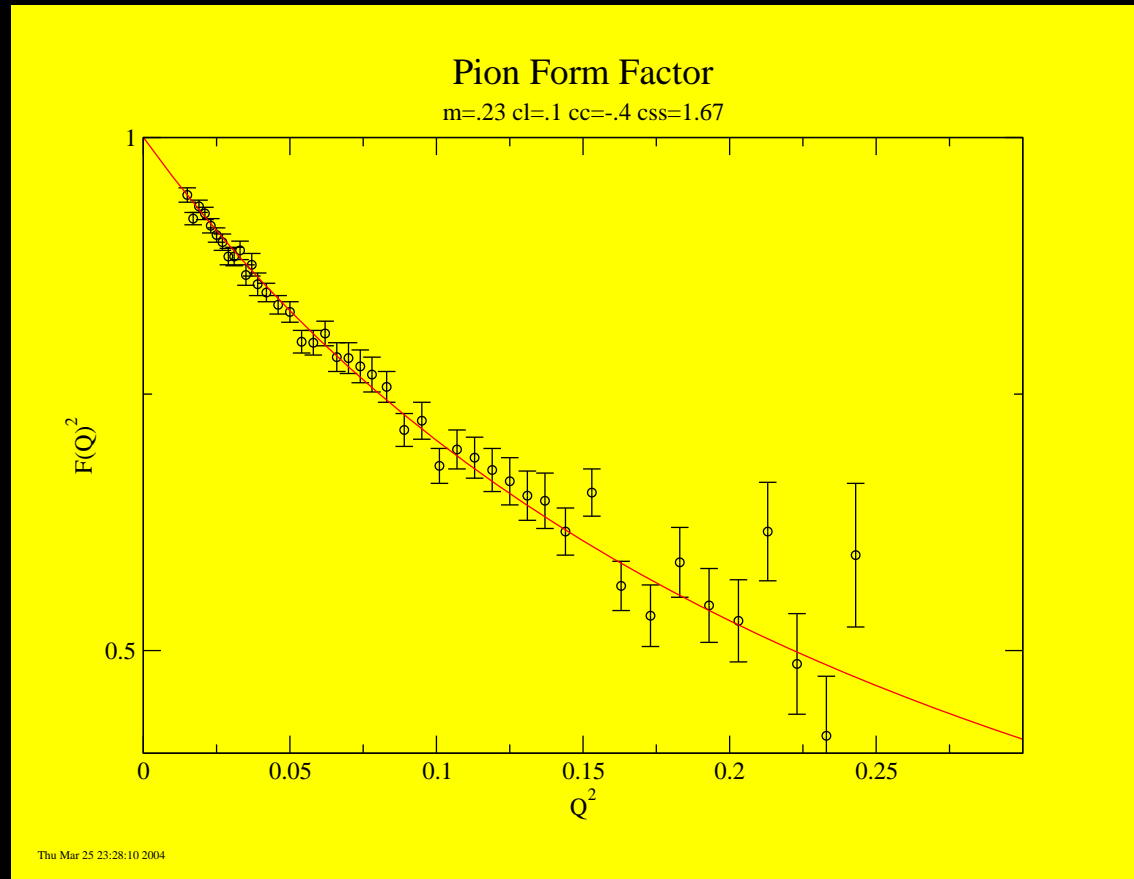
# Example

- Assume a model quark-antiquark Hamiltonian:

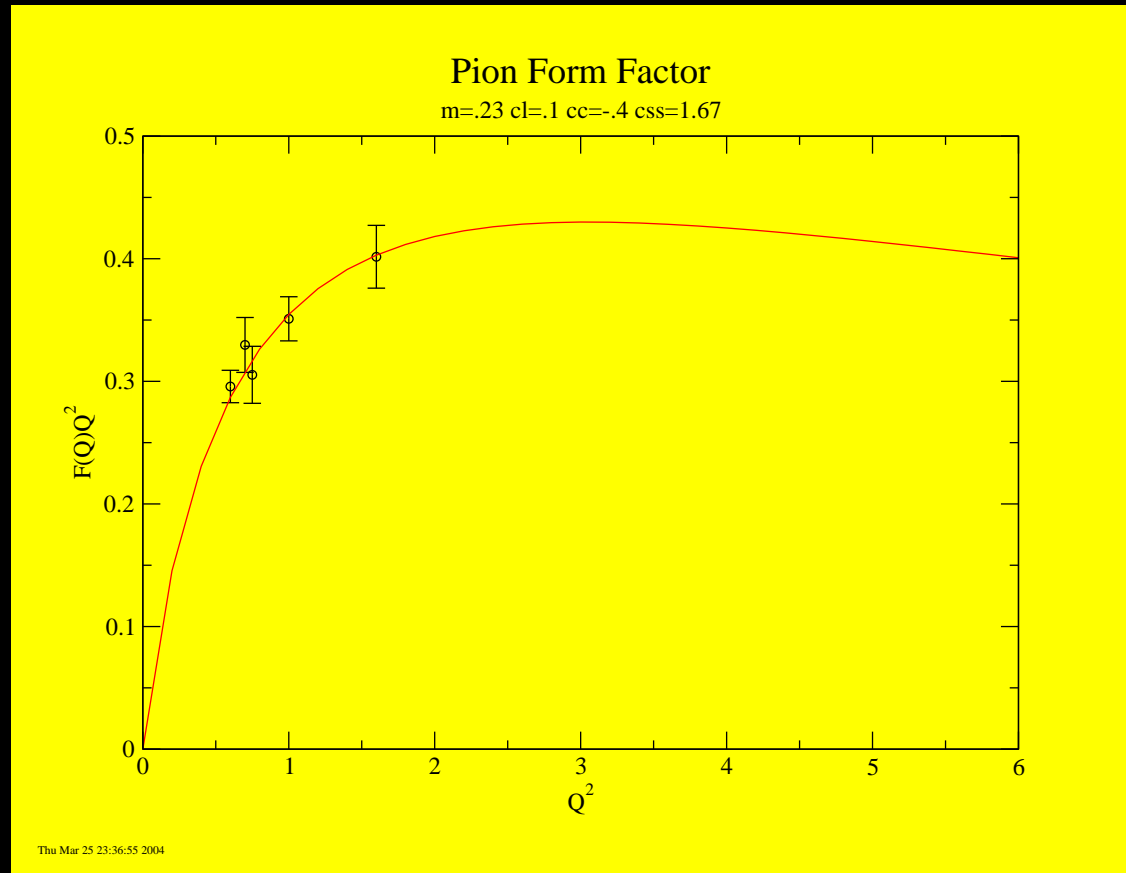
$$M = 2\sqrt{m^2 + p^2} + \alpha r - \frac{\beta}{r} + \gamma \vec{s}_1 \cdot \vec{s}_2 e^{-\lambda r^2}$$

- Choose model parameters to fit experimental data.
- Use the resulting model to make predictions.

# Pion form factor



# Pion form factor



# Pion form factor

- This example makes a prediction, based on a relativistic model, for proposed measurements.
- The nominal RMS radius of the pion in this model is 3.88 fm, which is slightly more than half of the charge radius. This large difference is a relativistic effect.

# Quantum Theory

- States are represented by unit vectors,  $|\psi\rangle$ , in a complex vector space

$$\langle\phi|\psi\rangle = \langle\psi|\phi\rangle^*$$

- The predictions of a quantum theory are the probabilities

$$P_{\psi\phi} = |\langle\psi|\phi\rangle|^2$$

# Relativity

- Inertial coordinate systems are coordinate systems where **free** particles move with constant velocity.
- The probabilities measured in equivalent experiments done in different inertial coordinate systems are identical.

# Relativity

- Because solutions of the Schrödinger equation are **not** observable in quantum theory, relativity does **not** require that the Schrödinger equation have the same form in every inertial coordinate system.
- This is an important difference between the classical and quantum formulation of relativistic invariance.

# Relativistic Invariance

- Galilean Relativity:  $X$  and  $X'$  inertial  $\Rightarrow$

$$|\Delta \vec{x}_{ij}| = |\Delta \vec{x}'_{ij}|$$

$$\Delta t_{ij} = \Delta t'_{ij}$$

- Special Relativity:  $X$  and  $X'$  inertial  $\Rightarrow$

$$|\Delta \vec{x}_{ij}|^2 - c^2 |\Delta t_{ij}|^2 = |\Delta \vec{x}'_{ij}|^2 - c^2 |\Delta t'_{ij}|^2$$

# Relativity

- The Michelson-Morley experiment verified that **special relativity** gives the observed relation between inertial coordinate systems.
- The most general transformation relating two inertial coordinate systems is a Poincaré transformation:

$$x^\mu \rightarrow x'^\mu = \Lambda^\mu{}_\nu x^\nu + a^\mu$$

$$g^{\mu\nu} = \Lambda^\mu{}_\alpha \Lambda^\nu{}_\beta g^{\alpha\beta}$$

# Relativity in Quantum Theory

$$X \rightarrow X'$$

$$|\phi\rangle, |\psi\rangle \rightarrow |\phi'\rangle, |\psi'\rangle$$

$$\Downarrow$$

$$|\langle\phi|\psi\rangle|^2 = |\langle\phi'|\psi'\rangle|^2$$

- Must hold for all  $|\psi\rangle, |\phi\rangle$  and all inertial coordinate systems  $X$  and  $X'$

# Wigner's Theorem

$$|\langle \phi | \psi \rangle|^2 = |\langle \phi' | \psi' \rangle|^2$$

$\Downarrow$

$$|\phi'\rangle = U|\phi\rangle \quad |\psi'\rangle = U|\psi\rangle \quad \langle \psi' | \phi' \rangle = \langle \psi | \phi \rangle$$

or

$$|\phi'\rangle = A|\phi\rangle \quad |\psi'\rangle = A|\psi\rangle \quad \langle \psi' | \phi' \rangle = \langle \psi | \phi \rangle^*$$

# Wigner's Theorem

- For rotations, translations, and rotationless Lorentz transformations:

$$U = U^{1/2}U^{1/2} \quad A = A^{1/2}A^{1/2}$$

- The correspondence between states must be unitary!



$$|\psi'\rangle = U|\psi\rangle$$

# Wigner's Theorem

$$\begin{array}{c} X \xrightarrow{\quad} X' \xrightarrow{\quad} X'' \\ \underbrace{\hspace{1.5cm}} \quad \underbrace{\hspace{1.5cm}} \\ (\Lambda, a) \quad (\Lambda', a') \\ \underbrace{\hspace{3.5cm}} \\ (\Lambda'', a'') \end{array}$$

$\Downarrow$

$$U(\Lambda', a')U(\Lambda, a) = U(\Lambda'\Lambda, \Lambda'a + a')$$

- $U(\Lambda, a)$  is a unitary representation of the Poincaré group

# Elements of Relativistic Quantum Theory

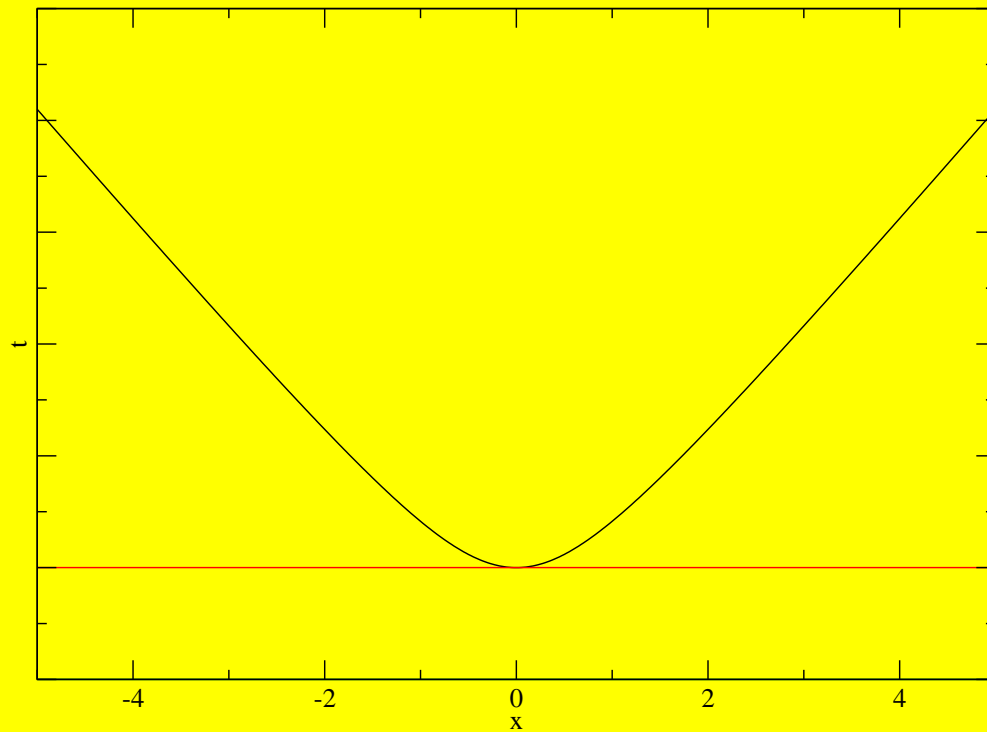
- Complex vector space,  $\mathcal{V}$  (Hilbert space)
- Unitary representation of the Poincaré group

$$U(\Lambda, a) : \mathcal{V} \rightarrow \mathcal{V}$$

- $U(\Lambda, a)$  contains the dynamics (time evolution).

# Dynamics

Space Time Diagram



# Dynamics

$$\Lambda = \begin{pmatrix} \gamma & 0 & 0 & \gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \gamma\beta & 0 & 0 & \gamma \end{pmatrix}$$

$$\vec{a} = (0, 0, 0, z) \quad \vec{b} = (0, 0, 0, -\gamma z) \quad t := (\gamma\beta z, \vec{0})$$

$$(\Lambda^{-1}, \vec{b})(\Lambda, \vec{a}) = (I, (t, \vec{0}))$$

# Dynamics

$$U(\Lambda, a) = e^{-i \sum \lambda_i G_i}$$

$$G_i = G_i^\dagger \quad G_i \in \{H, \vec{P}, \vec{J}, \vec{K}\}$$

$$[G_i, G_j] = i g_{ijk} G_k$$



$$[P_i, K_j] = i \delta_{ij} H$$

# Dynamics

- Galilean Invariant Dynamics  $\{H, \vec{P}, \vec{J}, \vec{K}, M\}$

$$[P_i, K_j] = i\delta_{ij}M$$

- Poincaré Invariant Dynamics  $\{H, \vec{P}, \vec{J}, \vec{K}\}$

$$[P_i, K_j] = i\delta_{ij}(H_0 + V)$$

- Puts non-linear constraints on  $\{H, \vec{P}, \vec{J}, \vec{K}\}$  for consistent initial value problem!

# One-Particle Relativistic Quantum Mechanics

## Problem

- Find the single particle Hilbert space  $\mathcal{V}$
- Find  $U(\Lambda, a)$  on  $\mathcal{V}$

# One-Particle Relativistic Quantum Mechanics

$$|\langle \Psi | \Phi \rangle| = |\langle \Psi' | \Phi' \rangle|$$



$$U(\Lambda, a)$$



$$\{H, \vec{P}, \vec{J}, \vec{K}\}$$



# One-Particle Relativistic Quantum Mechanics

- Construct a maximal set of commuting Hermitian operators out of  $\{H, \vec{P}, \vec{J}, \vec{K}\}$ :
- Use the commutations relations of  $\{H, \vec{P}, \vec{J}, \vec{K}\}$  to determine the eigenvalues of these operators.
- Let  $\mathcal{V}$  be the space of square integrable functions of the eigenvalues.
- Use the transformation properties of the observables to determine  $U(\Lambda, a)$ .

# Commuting Observables

$$\{M, j^2, \vec{P}, \vec{j}_z\}$$

where

$$M := \sqrt{H^2 - \vec{P} \cdot \vec{P}}$$

$$\vec{j} = \vec{J} + \frac{1}{2} \left\{ \frac{1}{H}, \vec{K} \right\} \times \vec{P} + \frac{(\vec{P} \times (H\vec{J} - \vec{P} \times \vec{K})) \times \vec{P}}{MH(M + H)}$$

# Commuting Observables

- The mass and spin of the particle fix the eigenvalue of  $m$  and  $j^2$
- The commutation relations imply

$$[j_x, j_y] = ij_z \cdots$$

- which means  $j$  must be integer or half integer and

$$\vec{j}_z \in \{-j, -j + 1, \cdots, j - 1, j\}$$

# One-Particle Hilbert Space

- Lorentz transformations can generate any momentum  $\Rightarrow -\infty < P^i < \infty$

$$\Psi(\vec{p}, \mu) = \langle m, j; \vec{p}, \mu | \Psi \rangle$$

$$\langle \Psi | \Phi \rangle := \sum_{\mu=-j}^j \int d^3p \Psi^*(\vec{p}, \mu) \Phi(\vec{p}, \mu)$$

$$\langle \Psi | \Psi \rangle < \infty$$

# Basis vectors

- Start with eigenstate with  $\vec{P} = \vec{0}$  and  $j_z = j$ :

$$|(m, j)\vec{0}, j\rangle := |\vec{0}, j\rangle$$

- Define the lowering operator  $j_- = j_x - ij_y$

$$|\vec{0}, \mu - 1\rangle = \frac{1}{\sqrt{(j + \mu)(j - \mu + 1)}} j_- |\vec{0}, \mu\rangle$$

- This defines

$$|m, j; \vec{0}, \mu\rangle := |\vec{0}, \mu\rangle$$

# Basis vectors

- The commutation relations  $[j_x, j_y] = ij_z \dots$  and definitions imply for any rotation  $R$

$$U(R, 0)|\vec{0}, \mu\rangle = \sum_{\mu'=-j}^j |\vec{0}, \mu'\rangle D_{\mu'\mu}^j(R)$$

# Basis vectors

- Let

$$\Lambda(\vec{p}) : (m, \vec{0}) = (\sqrt{\vec{p}^2 + m^2}, \vec{p}) :$$

$$|\vec{p}, \mu\rangle := U(\Lambda(\vec{p}), 0)|\vec{0}, \mu\rangle \left(1 + \frac{\vec{p}^2}{m^2}\right)^{-1/4}$$

- the factor  $\left(1 + \frac{\vec{p}^2}{m^2}\right)^{-1/4}$  is determined by the requirement that  $U(\Lambda, 0)$  be unitary.

$$U(I, a)|\vec{0}, \mu\rangle := e^{-ia^0 m}|\vec{0}, \mu\rangle$$

# One-Body Problem

- Any Poincare transformation can be decomposed into a product of the previously defined transformations

$$U(\Lambda, a) = U(\Lambda(p'), 0)U(I, \Lambda^{-1}(p')a) \times \\ U(\underbrace{\Lambda^{-1}(p')\Lambda\Lambda(p)}_{\text{rotation}}, 0)U(\Lambda^{-1}(p), 0)$$

$$p' = \Lambda p$$

# The two-body problem

- The one-body solution is well known.
- It provides clues on how to solve the two-body problem

# The Currie Jordan Sudarshan Theorem

$$\{X_i, P_j\} = \delta_{ij}$$

$$\{X_i, J_j\} = \epsilon_{ijk} X_k$$

$$\{X_i, K_j\} = X_j \{X_i, H\} \quad \text{world-line condition}$$

- Poisson brackets of  $\{H, \vec{P}, \vec{J}, \vec{K}\}$  satisfy Lie algebra of Poincaré group.

# The Currie-Jordan-Sudarshan Theorem



- Can only be satisfied for free particles!
- The CJS theorem suggests that it might be difficult to formulate relativistic models for systems of interacting particles.
- The out in relativistic quantum mechanics is that there is no position operator!

# Position

- Let  $|\vec{0}, 0\rangle$  be a vector corresponding to a particle at the origin at time  $t = 0$

$$\langle \vec{p} | \vec{0}; 0 \rangle = \langle \vec{p} = 0 | U^\dagger(\Lambda(\vec{p}), 0) U(\Lambda(\vec{p}), 0) | \vec{0}; 0 \rangle$$

$$= \frac{N}{(\vec{p}^2 + m^2)^{1/4}}$$

$$\langle \vec{p} | \vec{x}; t = 0 \rangle = \langle \vec{p} | U(I, \vec{x}) | \vec{0}; 0 \rangle$$

⇓

# Position

$$\langle \vec{p} | \vec{x} \rangle = \frac{e^{-i\vec{p}\cdot\vec{x}}}{(2\pi)^{3/2}(\vec{p}^2 + m^2)^{1/4}}$$

$$\langle \vec{0} | \vec{x} \rangle = \int \frac{d^3p}{(2\pi)^3(\vec{p}^2 + m^2)^{1/2}} e^{-i\vec{p}\cdot\vec{x}} =$$

$$\frac{ic^2}{2}(2\pi)^2 D_+(0, |\vec{x}|) \sim \left( \frac{mc|\vec{x}|}{\hbar} \right) e^{\frac{-mc|\vec{x}|}{\hbar}} \neq 0$$

# The Two-Body Problem

- The one-body solution has clues about how to solve the two-body problem
- Find  $M, j^2, \vec{P}, j_z$  for the **non-interacting** two-body system.
- Construct basis of simultaneous eigenstates of these operators

# The Two-Body Problem

- Add interactions to  $M$  that commute with and do not depend on  $\vec{P}$  and  $j_z$
- Construct simultaneous eigenstates of  $M + V, j^2, \vec{P}, j_z$
- Construct  $U(\Lambda, a)$  following the one body construction

# The Two-Body Problem

- Construct

$$\langle \vec{p}_1, \mu_1; \vec{p}_1, \mu_1 | m_{12}, j_{12}; \vec{p}_{12}, \mu_{12}; l_{12}, s_{12} \rangle$$

⇓

$$| m_{12}, j_{12}; \vec{p}_{12}, \mu_{12}; l_{12}, s_{12} \rangle$$

- The coefficients above differ from the corresponding non-relativistic coefficients.

# Two-Body Problem

$$\begin{aligned} \langle m_{12}, j_{12}; \vec{p}_{12}, \mu_{12}; l_{12}, s_{12} | V | m'_{12}, j'_{12}; \vec{p}'_{12}, \mu'_{12}; l'_{12}, s'_{12} \rangle = \\ \delta(\vec{p}_{12} - \vec{p}'_{12}) \delta_{j_{12} j'_{12}} \delta_{\mu_{12} \mu'_{12}} \langle m_{12}, l_{12}, s_{12} || V^j || m'_{12}, l'_{12}, s'_{12} \rangle \\ \Downarrow \\ |M, j_{12}; \vec{p}_{12}, \mu_{12} \rangle \end{aligned}$$

# Two-Body Problem

$$|M, j_{12}; \vec{0}_{12}, j_{12}\rangle$$

$$\Downarrow \quad (j_{12}-)$$

$$|M, j_{12}; \vec{0}_{12}, \mu_{12}\rangle$$

$$\Downarrow \quad (U(\Lambda(p)))$$

$$|M, j_{12}; \vec{p}_{12}, \mu_{12}\rangle$$

# The Two-Body Problem



$$U_I(\Lambda, a) |M, j_{12}; \vec{p}_{12}, \mu_{12}\rangle$$

- This construction leads to a  $U(\Lambda, a)$  for the interacting system on the two body Hilbert space.
- The dynamical problem is to diagonalize  $M = m_{12} + V$  in the basis of free particle eigenstates.

# Beyond-Two

- The construction has been generalized to treat any number of particle and with limited particle production.
- The requirement of cluster properties adds new dynamical non-linear constraints for more than two particles. They have been treated.
- $U(\Lambda, a)$  implies that spinor, tensor, and four vector operators are interaction dependent

# Conclusions

- Relativistic quantum mechanics of particles is a useful and practical tool for modeling quantum systems where relativity is important.
- It has been successfully applied to model spectral, electromagnetic, and scaling properties of baryons, mesons, and the two and three nucleon systems.
- Open questions on how to treat problems with particle production are being explored