

Lecture 5

adding angular momentum

$$[\bar{J}_a, \bar{J}_b] = 0$$

define

$$\vec{J}_{ab} = \vec{J}_a + \vec{J}_b$$

homework

$$[J_{ab}^i, J_{ab}^j] = i \sum_{k=1}^3 \epsilon_{ijk} J_{ab}^k$$

this means that we can find simultaneous eigenstates of \vec{J}_{ab}^2 and J_{ab}^z

$$|J_{ab} \mu_{ab}\rangle$$

the problem is to find these eigenstates as a linear combination of the states

$$|j_a \mu_a j_b \mu_b\rangle$$

$$|J_{ab} \mu_{ab}\rangle = \sum_{\mu_a \mu_b} |j_a \mu_a j_b \mu_b\rangle \langle j_a \mu_a j_b \mu_b | J_{ab} \mu_{ab}\rangle$$

where the coefficients

$$\langle j_a \mu_a j_b \mu_b | J_{ab} \mu_{ab}\rangle \equiv C_{\mu_a \mu_b}^{j_a j_b J_{ab} \mu_{ab}}$$

are called Clebsch Gordan coefficients

For the construction we use

$$J_{\mp} J_{\pm} = \bar{J}^2 - J_z^2 \mp J_z = J^2 - J_z(J_z \pm 1)$$

This can be solved for

$$J^2 = J_{-} J_{+} + J_z(J_z + 1)$$

we start by considering

$$J_{ab}^z |j_a j_a j_b j_b\rangle = (J_a^z + J_b^z) |j_a j_c j_b j_b\rangle = (j_a + j_b) |j_c j_a j_b j_b\rangle$$

$$\begin{aligned} J_{ab}^2 |j_a j_c j_b j_b\rangle &= (J_{ab-} J_{ab+} + J_z(J_z + 1)) |j_c j_a j_b j_b\rangle \\ &= (0 + (j_c + j_b)(j_c + j_b + 1)) |j_c j_c j_b j_b\rangle \end{aligned}$$

since

$$J_{ab+} |j_c j_c j_b j_b\rangle = (J_{a+} + J_{b+}) |j_a j_c j_b j_c\rangle = 0$$

* This means that $|j_c j_c j_b j_b\rangle$ is an eigenstate of J_{ab}^z \bar{J}_{ab}^2 with eigenvalues $j_{ab}(j_{ab} + 1)$ $j_{cb} = j_c + j_b$

* it is also a highest weight state since

$$J_{+ab} |j_a j_c j_b j_d\rangle = 0$$

we define:

$$|j_a^+ j_b, j_c^+ j_d\rangle \equiv |j_a j_c j_b j_d\rangle$$

Recall as a consequence of the commutation relations

$$J_{\pm} |j, m\rangle = |j, m \pm 1\rangle \sqrt{(j \mp m)(j \pm m + 1)}$$

using $J_{ab}^- = J_a^- + J_b^-$ on $|j_a^+ j_b, j_c^+ j_d\rangle$ gives

$$J_- |j_a^+ j_b, j_c^+ j_d\rangle =$$

$$|j_a^+ j_b, j_c^+ j_d - 1\rangle \sqrt{2(j_a + j_b) \cdot 1} =$$

$$(J_{a-} + J_{b-}) |j_a j_c j_b j_d\rangle =$$

$$|j_a j_c j_b j_d - 1\rangle \sqrt{2j_b} + |j_a j_c - 1, j_b j_d\rangle \sqrt{2j_a}$$

comparing both sides of this equation gives

$$|j_a + j_b, j_a + j_b - 1\rangle = \sqrt{\frac{j_b}{j_a + j_b}} |j_a j_a j_b j_b - 1\rangle + \sqrt{\frac{j_a}{j_a + j_b}} |j_a j_a - 1 j_b j_b\rangle$$

this means

$$\begin{cases} \langle j_a + j_b, j_a + j_b - 1 | j_a j_a j_b j_b - 1 \rangle = \sqrt{\frac{j_b}{j_a + j_b}} \\ \langle j_a + j_b, j_a + j_b - 1 | j_a j_a - 1 j_b j_b \rangle = \sqrt{\frac{j_a}{j_a + j_b}} \end{cases}$$

we can continue by applying $\bar{J}_{ab} = \bar{J}_a + \bar{J}_b$ to both sides of this equation

this generates all states of the form

$$|j_a + j_b, u\rangle \quad - (j_a + j_b) \leq u \leq (j_a + j_b)$$

* there are $2(j_a + j_b) + 1$ such states

* for these states all of the Clebsch Gordan coefficients are positive

since there is only one state with $M_{ab} = j_a + j_b$ it is the state $|j_a j_c j_b j_b\rangle$

there are 2 states with $M_{ab} = j_a + j_b - 1$
there are

$$|j_a j_c j_b j_{b-1}\rangle, |j_c j_{c-1}, j_b j_b\rangle$$

one of the states is $|j_c + j_b, j_c + j_b - 1\rangle$

consider the orthogonal complement

$$|X\rangle = \sqrt{\frac{j_a}{j_a + j_b}} |j_a j_c j_b j_{b-1}\rangle - \sqrt{\frac{j_b}{j_a + j_b}} |j_c j_{c-1} j_b j_b\rangle$$

$$* (J_c^2 + J_a^2) |X\rangle = (j_c + j_b - 1) |X\rangle$$

$$J_{ab}^+ |X\rangle = \sqrt{\frac{j_a}{j_a + j_b}} |j_a j_a j_b j_b\rangle \times \sqrt{2j_b} \\ - \sqrt{\frac{j_b}{j_a + j_b}} |j_a j_c j_b j_b\rangle \sqrt{2j_c} = 0$$

$$J_{ab}^2 |X\rangle = (J_- J_+ + (J_{abz} + 1)(J_{caz})) |X\rangle \\ = (j_a + j_b - 1)(j_a + j_b) |X\rangle$$

these equations imply that $|X\rangle$
is an eigenstate of J_{ab}^2 and J_{ab}^z
with eigenvalues

$$M_{ab} = j_a + j_b - 1 \quad j_{ab} = j_a + j_b - 1$$

It is also a highest weight state
 In this case while this state
 is normalized we need to
 assign a phase.

* we can choose the coefficients
 to be real by taking the normalization
 $= \pm 1$.

To choose the sign if $j_a \geq j_b$
 choose the coefficient of $|j_a, j_a, j_b, j_b\rangle$
 to be positive. This is just
 a convention - it is fairly
 standard (but not required in
 principle - called the Condon-
 shortly convention)

using the lowering operator we
 can then calculate all $2(j_a + j_b + 1) + 1$
 states with $j = j_a + j_b - 1$

Next we note there are 3 states with
 $j = j_c + j_b - 2$

$$|j_c j_c j_b j_b - 2\rangle \quad |j_c j_c - 1 j_b j_b - 1\rangle \quad |j_c j_c - 2 j_b j_b\rangle$$

there are 2 state with $j > j_c + j_b - 2$.

It is possible to show that the
 orthogonal complement is
 a highest weight state of J_{ab}^2 J_{ab}^z
 with $j = j_c + j_b - 2$.

* The normalization can again
 be fixed by the Condon
 Shortly convention

* Lowering operators can be
 used to construct $|j_c + j_b - 2, u\rangle$
 $- (j_c + j_b - 2) \leq u \leq (j_c + j_b - 2)$

this process can be continued
 until

$$j_{ab} = |j_c - j_b| = j_c - j_b \quad (\text{for } j_c \geq j_b)$$

This gives

$$N = \sum_{j=|j_c-j_h|}^{|j_c+j_h|} (2j+1) \stackrel{?}{=} (2j_c+1)(2j_h+1)$$

Homework!

simultaneous eigenstates of J_{cb}^2
and J_{ah}^2

this generates all Clebsch-Gordan coefficients

consider

$$\langle j_a m_a j_b m_b | e^{-i\vec{\theta} \cdot (J_a + J_b)} | j_c m_c j_h m_h \rangle =$$

$$\langle j_c m_c | e^{-i\vec{\theta} \cdot J_a} | j_a m_a \rangle \langle j_b m_b | e^{-i\vec{\theta} \cdot J_b} | j_h m_h \rangle =$$

$$D_{m_c m_a}^{j_c}(R) D_{m_b m_h}^{j_b}(R) =$$

$$\sum_{j_h, m_h} \langle j_c m_c j_b m_b | j_a m_a \rangle \langle j_h m_h | e^{-i\vec{J}_{ab} \cdot \vec{\theta}} | j_a m_a \rangle$$

$$\langle j_a m_a j_b m_b | j_c m_c \rangle =$$

$$= \sum_{j=|j_a-j_b|}^{j_a+j_b} \sum_{u,v=-j}^j C_{u_a u_b u}^{j_a j_b j} D_{u_a u_b u}^{j_a j_b j}(R) C_{v_a v_b v}^{j_a j_b j}$$

$$= D_{u_a v_a}^{j_a}(R) D_{u_b v_b}^{j_b}(R)$$

Note: each of $|j_a u_a\rangle$ and $|j_b u_b\rangle$ transform among themselves under rotations.

The coefficients $C_{u_a u_b u}^{j_a j_b j}$ block diagonalized this matrix into parts that transform irreducibly

$$D^{j_a}(R) \otimes D^{j_b}(R) = \bigoplus_{j=|j_a-j_b|}^{j_a+j_b} D^j(R)$$

$$C(D^{j_a}(R) \otimes D^{j_b}(R)) e^{\dagger} = \begin{pmatrix} M_{j_a+j_b} & 0 & 0 & \dots \\ 0 & M_{j_a+j_b-1} & \dots & \dots \\ 0 & 0 & \dots & \dots \\ 0 & 0 & \dots & M_{|j_a-j_b|} \end{pmatrix}$$

The Clebsch Gordan coefficients block diagonalizes products of rotation matrices into invariant irreducible subspaces

Integration

$$\int D_{u_a v_c}^{j_a} (R) D_{u_b v_d}^{j_b} (R) dR =$$

$$\sum_{j=|j_a-j_b|}^{j_a+j_b} \sum_{u=-j}^j \sum_{v=-j}^j C_{u u_c v_b}^{j_a j_b j} \int D_{uv}^j (R) dR C_{v v_a u_d}^{j_a j_b j}$$

$$= C_{0 u_a u_b}^{0 j_a j_b} C_{0 v_a v_b}^{0 j_a j_b}$$

(this vanishes unless $j_a = j_b$; $u_a = -u_b$, $v_a = -v_b$)

this can be generalized to product of any number of $D_{uv}^j (R)$

It is also possible to perform integrals involving wigner matrices and their complex conjugates

$$\int D_{uv}^j (R) D_{u'v'}^{j'*} (R) dR = \frac{\delta_{jj'} \delta_{uu'} \delta_{vv'}}{2j+1}$$

To show this note

$$(1) \quad \sigma_2 \bar{G} G_2^* = -\bar{G}$$

$$\begin{aligned} R^* &= \left(e^{-i \frac{\sigma_2 \cdot \bar{G}}{2} \cdot \theta} \right)^* = \left(e^{i \frac{\sigma_2 \cdot \bar{G}}{2} \cdot \theta} \right) \\ &= \left(e^{i (-\sigma_2 \bar{G} \sigma_2) \cdot \theta/2} \right) = \\ &\quad \quad \quad -i \bar{G} \cdot \bar{G}/2 \\ &= \sigma_2 e \quad \sigma_2 \\ &= \sigma_2 R \sigma_2 \end{aligned}$$

$$(2) \quad R_Y(\pi) = \cos\left(\frac{\pi}{2}\right) I - i \sin\left(\frac{\pi}{2}\right) \sigma_2 = -i \sigma_2$$

$$R_Y^\dagger(\pi) = i \sigma_2 = R_Y^{-1}(\pi)$$

$$R^* = R_Y(\pi) R R_Y(-\pi)$$

(3) since $D_{uv}^\dagger(R)^* = D_{uv}^\dagger(R^*)$ (D has real coefficients)

$$D_{uv}^\dagger(R)^* = D_{uv}^\dagger(R^*) = D_{uv}^\dagger(R_Y(\pi) R R_Y(-\pi)) =$$

$$\sum D_{u\alpha}^\dagger(R_Y(\pi)) D_{\alpha\beta}^\dagger(R) D_{\beta v}^\dagger(R_Y(-\pi))$$

$$\int D_{u'v'}^{\dagger j'}(R) D_{uv}^{\dagger j}(R)^* dR =$$

$$\sum_{\alpha\beta} \int D_{u'v'}^{\dagger j'}(R) D_{uv}^{\dagger j}(R_Y(\pi)) D_{\alpha\beta}^{\dagger j'}(R) D_{\beta v}^{\dagger j}(R_Y(\pi)^{-1}) dR$$

$$\sum_{\alpha\beta} \int \sum C_{\tilde{u} u' \alpha}^{\tilde{j} j' j} C_{\tilde{v} v' \beta}^{\tilde{j} j' j} D_{\tilde{u}\tilde{v}}^{\tilde{j}}(R) D_{u\alpha}^{\dagger j}(R_Y(\pi)) D_{\beta v}^{\dagger j}(R_Y(\pi)^{-1})$$

doing the integral sets $\tilde{j} = \tilde{u} = \tilde{v} =$

$$\sum_{\alpha\beta} C_{0 u' \alpha}^{0 j' j} C_{0 v' \beta}^{0 j' j} D_{u\alpha}^{\dagger j}(R_Y(\pi)) D_{\beta v}^{\dagger j}(R_Y(\pi)^{-1})$$

For $C_{0 u' \alpha}^{0 j' j} \neq 0 \Rightarrow j' = j \quad \alpha = -u' \quad (\beta = -v')$

$$C_{0 u' -u'}^{0 j' j} C_{0 v' -v'}^{0 j' j} D_{u-u'}^{\dagger j}(R_Y(\pi)) D_{-v'v}^{\dagger j}(R_Y(\pi)^{-1}) \delta_{j'j}$$

at this point we need to consider the value of these quantities:

$$R_Y(\pi) = e^{-i\frac{\pi}{2}\sigma_Y} = \cos(\frac{\pi}{2}) - i\sigma_Y \sin(\frac{\pi}{2}) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$R_{++} = R_{--} = 0 \quad R_{-+} = -R_{+-} = 1$$

$$R_Y(\pi)^{-1} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

$$R_{++} = R_{--} = 0 \quad R_{+-} = -R_{-+} = -1$$

inserting these in the expression for $D_{uv}^{\dagger j}(R)$ and using the value of $C_{0 u-u}^{0 j' j}$ lead to

$$\begin{aligned} & C_{0 -u' u'}^{0 j' j} C_{0 v' v'}^{0 j' j} D_{u-u'}^{\dagger j}(R_Y(\pi)) D_{-v'v}^{\dagger j}(R_Y(\pi)^{-1}) \delta_{j'j} \\ &= \frac{\delta_{j'j} \delta_{uu'} \delta_{vv'}}{2j+1} \end{aligned}$$

This gives

$$\int D_{uv}^{j_1}(R) D_{uv}^{*j_1}(R) dR = \frac{\delta_{j_1 j_1} \delta_{u_1 u_1} \delta_{v_1 v_1}}{2j_1 + 1}$$

$$\int D_{uv}^j(R) dR = \delta_{j_0} \delta_{u_0} \delta_{v_0}$$

Using these relations and the Clebsch equation we can compute integrals over arbitrary products of $D(R)$ and $D^*(R)$ - with the Clebsch-Gordan coefficients can be reduced to one of the above integrals.

Note

$$Y_l^m(\theta, \phi) = \langle \hat{r} | l m \rangle$$

\hat{r} = unit vector with polar angles θ, ϕ .

Active transformation:

$$\hat{r} = R_z(\phi) R_y(\theta) \hat{z}$$



$$\langle \mathcal{U}(R) \hat{z} | l m \rangle =$$

$$\langle \hat{z} | \mathcal{U}^\dagger(R) | l m \rangle =$$

$$\sum \langle \hat{z} | l m' \rangle \langle l m' | \mathcal{U}^\dagger(R) | l m \rangle$$

$$\sum \langle \hat{z} | l m' \rangle \langle l m | \mathcal{U}(R) | l m' \rangle^*$$

where

$$\langle \hat{z} | l m \rangle = Y_l^m(0, 0) = S_{m0} \sqrt{\frac{2l+1}{4\pi}}$$

$$Y_l^m(\theta, \phi) = \sqrt{\frac{2l+1}{4\pi}} D_{m0}^{l*}(R_z(\phi) R_y(\theta))$$

note

$$\begin{aligned} D_{m_0}^{\rho}(R_z(\phi) R_y(\theta)) &= D_{m_0}^{\rho}(R_z(\phi) R_y(\theta) R_z(\psi)) \\ &= e^{-im\phi} D_{m_0}^{\rho}(R_y(\theta)) \underbrace{e^{-i0\psi}}_1 \\ &= D_{m_0}^{\rho}(R) \end{aligned}$$

This means that we can use this to compute integrals involving $D(R)$ and spherical harmonics

$$\int Y_e^m(\theta, \phi) Y_{e'}^{m'}(\theta, \phi) \sin\theta d\theta d\phi =$$

$$8\pi \int Y_e^m(\theta, \phi) Y_{e'}^{m'}(\theta, \phi) dR =$$

$$8\pi \times \sqrt{\frac{2e+1}{4\pi}} \sqrt{\frac{2e'+1}{4\pi}} D_{m_0}^{e, x}(R) D_{m'_0}^{e', y}(R) dR$$

$$2 \sqrt{(2e+1)(2e'+1)} \begin{pmatrix} \tilde{e} & e & e' \\ \tilde{m} & m & m' \end{pmatrix} \begin{pmatrix} \tilde{e} & e & e' \\ \tilde{n} & 0 & 0 \end{pmatrix} D_{\tilde{m}\tilde{n}}^{\tilde{e}}(R) dR$$

$$2 \sqrt{(2e+1)(2e'+1)} \begin{pmatrix} 0 & e & e' \\ 0 & m & m' \end{pmatrix} \begin{pmatrix} 0 & e & e' \\ 0 & 0 & 0 \end{pmatrix}$$

This requires $e=e'$ $m'=-m$

This can be generalized to more complicated integrals

This can be abstracted to any quantity $V^{i_1 \dots i_n}$ that transforms like

$$V^{i_1 \dots i_n} \rightarrow \tilde{V}^{i_1 \dots i_n} = \sum V^{j_1 \dots j_n} R_{j_1 i_1} \dots R_{j_n i_n}$$

is called a rank n spherical tensor operator

Consider $x^i x^j$ the dot product $\delta_{ij} x^i x^j$ and cross product $\epsilon_{ijk} x^i x^j$ transform like scalars and vectors under rotations. The remaining 5 independent components transform like a traceless symmetric tensor.

The scalar, vector and tensor transform independently under rotations.

Note

$$\begin{aligned} Y_0^1 &= \sqrt{\frac{3}{4\pi}} \cos\theta & Y_1^1 &= -\sqrt{\frac{3}{8\pi}} \sin\theta e^{i\phi} & \tilde{Y}_1^1 &= \sqrt{\frac{3}{8\pi}} \sin\theta e^{-i\phi} \\ &= \sqrt{\frac{3}{4\pi}} \frac{z}{r} & &= -\sqrt{\frac{3}{4\pi}} \frac{x+iy}{\sqrt{2}} & &= \sqrt{\frac{3}{4\pi}} \frac{x-iy}{\sqrt{2}} \end{aligned}$$

For the vectors $\vec{x} = x, y, z$ define the spherical components of \vec{x} by

$$x_{-1}^0 = z \quad x_1^1 = -\frac{x-iy}{\sqrt{2}} \quad x_{-1}^1 = \frac{x-iy}{\sqrt{2}}$$

Spherical Tensors

Consider a charge density $\rho(\vec{r}')$ and the associated potential

$$V(\vec{r}) = \int \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} d\tau' = \frac{1}{r} \int \frac{\rho(\vec{r}')}{\sqrt{1 - 2\hat{r} \cdot \frac{\vec{r}'}{r} + \left(\frac{\vec{r}'}{r}\right)^2}} d\tau'$$

For a finite charge density with $|\vec{r}| \gg$ than the size of the charge distribution $\left|\frac{\vec{r}'}{r}\right| \ll 1$ $\vec{u} = \frac{\vec{r}'}{r}$

$$\frac{1}{\sqrt{1 - 2\hat{r} \cdot \vec{u} + u^2}} \rightarrow 1 + \frac{\partial_i}{\partial u} \left(\frac{1}{\sqrt{1 - 2\hat{r} \cdot \vec{u} + u^2}} \right) \Big|_{u=0} \frac{x'_i}{r} + \frac{1}{2!} \frac{\partial^2}{\partial u_i \partial u_j} \left(\frac{1}{\sqrt{1 - 2\hat{r} \cdot \vec{u} + u^2}} \right) \Big|_{u=0} \frac{x'_i x'_j}{r^2} + \frac{1}{3!} \frac{\partial^3}{\partial u_i \partial u_j \partial u_k} \left(\frac{1}{\sqrt{1 - 2\hat{r} \cdot \vec{u} + u^2}} \right) \Big|_{u=0} \frac{x'_i x'_j x'_k}{r^3} + \dots$$

The important thing is that this multipole expansion involves coefficients multiplied by quantities that look like products of vectors

If we consider $V(R\vec{r})$ each one of the components rotates

$$x_i x_j x_k \rightarrow x'_i x'_j x'_k = \sum R_{ii'} R_{jj'} R_{kk'} x_i x_j x_k \\ = \sum x_i x_j x_k R_{ii'} R_{jj'} R_{kk'}$$

The terms in the multipole expansion are tensors

$$\left(V(R\vec{r}) = \int \frac{\rho(\vec{r}')}{|R\vec{r} - \vec{r}'|} d\tau' = \int \frac{\rho(\vec{r}')}{|r - R^{-1}\vec{r}'|} d\tau' \right)$$

These transform like

$$U(R) X_i^m U^\dagger(R) = \sum X_i^{m'} D_{m'm}^l(R)$$

clearly we can extract the cartesian components from the spherical components

We generalize this to define a spherical tensor operator as an operator that transforms like

$$U(R) X_j^m U^\dagger(R) = \sum_j X_j^{m'} D_{m'm}^l(R)$$

The Wigner Eckart Theorem

considers matrix elements of a spherical tensor operator in an angular momentum basis

$$\langle j_a, m_a | V_{j_b}^{j_c} | j_c, m_c \rangle$$

Claim: this is proportional to

$$C \begin{matrix} j_a & j_b & j_c \\ m_a & m_b & m_c \\ j_c & j_b & j_a \end{matrix}$$

proof

$$\langle j_a v_a | V_{j_b}^{j_b} | j_c v_c \rangle =$$

$$\int \langle j_a v_a | u^\dagger(R) u(R) V_{j_b}^{j_b} u^\dagger(R) u(R) | j_c v_c \rangle dR$$

$$\sum \int D_{m_a v_a}^{j_a}(R) \langle j_a m_a | V_{j_b}^{j_b} | j_c m_c \rangle D_{m_b m_c}^{j_b}(R) D_{m_a v_c}^{j_c}(R) dR$$

$$\sum \int D_{m_a v_c}^{j_a}(R) \langle j_a m_a | V_{j_b}^{j_b} | j_c m_c \rangle \times$$

$$C_{m_a m_b m_c}^{j_a j_b j_c} C_{v_a v_b v_c}^{j_a j_b j_c} D_{m_a v_c}^{j_c}(R) dR$$

$$\frac{1}{2j_c+1} C_{v_a v_b v_c}^{j_a j_b j_c} \left[\sum_{m_a m_b m_c} C_{m_a m_b m_c}^{j_a j_b j_c} \langle j_a m_a | V_{j_b}^{j_b} | j_c m_c \rangle \right]$$

all of the m 's are summed here so this is a constant that depends on $j_a j_b j_c$

$$= \frac{C_{j_a j_b j_c}}{\sqrt{2j_c+1}} \times \langle j_a || V_{j_b} || j_c \rangle$$

↑ reduced matrix element

where

$$\langle j_c || V_{j_b} || j_a \rangle = \frac{1}{\sqrt{2j_c+1}} \sum_{m_a m_b m_c} C_{m_a m_b m_c}^{j_a j_b j_c} \langle j_a m_a | V_{j_b}^{j_b} | j_c m_c \rangle$$

Since $C \begin{matrix} j_a j_b j_c \\ v_a v_b v_c \end{matrix} = 0$ unless

$\left. \begin{array}{l} |j_b - j_c| \leq j_a \leq |j_b + j_c| \\ v_a = v_b + v_c \end{array} \right\}$ selection rules

$$\frac{\langle j_a v_a | V_{j_b}^{v_b} | j_b v_b \rangle}{\langle j_a v_a' | V_{j_b}^{v_b'} | j_b v_b' \rangle} = \frac{C \begin{matrix} j_a j_b j_c \\ v_a v_b v_c \end{matrix}}{C \begin{matrix} j_a j_b j_c \\ v_a' v_b' v_c' \end{matrix}}$$