

$$\begin{aligned}
 \text{1 a. } \rho &= \epsilon_0 \nabla \cdot \vec{E} \\
 &= \epsilon_0 \cdot \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \vec{E}_r) \\
 &= \epsilon_0 \cdot \frac{1}{r^2} \cdot \frac{\partial}{\partial r} (Ar^4) \\
 &= \boxed{4A\epsilon_0 r}
 \end{aligned}$$

$$\begin{aligned}
 \text{b. } Q &= \int \rho dV = 4\pi \int_0^R 4A\epsilon_0 r \cdot r^2 dr \\
 &= 16\pi \epsilon_0 A \cdot \frac{r^4}{4} \Big|_0^R \\
 &= \boxed{4\pi \epsilon_0 A R^4}
 \end{aligned}$$

$$\vec{E} = \frac{Q}{4\pi \epsilon_0 r^2} \hat{r} = \boxed{\frac{AR^4}{r^2} \hat{r}}$$

$$\text{c. } V(r) = -\int_{\infty}^r E_r dr$$

$$\begin{aligned}
 r > R; \quad V(r) &= -\int_{\infty}^r \frac{AR^4}{r^2} dr \\
 &= \frac{AR^4}{r} \Big|_{\infty}^r = \boxed{\frac{AR^4}{r}}
 \end{aligned}$$

$$\begin{aligned}
 r < R; \quad V(r) &= -\int_{\infty}^R \frac{AR^4}{r^2} dr - \int_R^r Ar^2 dr \\
 &= AR^3 - Ar^3/3 \Big|_R^r \\
 &= AR^3 - Ar^3/3 + AR^3/3 \\
 &= \boxed{\frac{4}{3}AR^3 - Ar^3/3}
 \end{aligned}$$

V continuous @ $r = R$
 \checkmark $V(R) = AR^3$

$$2. \rho(\vec{r}) = q \delta^3(\vec{r} - \vec{r}_1) - q \delta^3(\vec{r} - \vec{r}_2)$$

$$3.a. V_{in}(r, \theta) = V_A + V_0 \frac{r}{R} \cos \theta$$

$$V_{out}(r, \theta) = V_A \frac{R}{r} + V_0 \frac{R^2}{r^2} \cos \theta$$

Matches @ $r = R$

$$b. \Delta \left(\frac{\partial V}{\partial n} \right) = \Delta \left. \frac{\partial V}{\partial r} \right|_R = -\sigma / \epsilon_0$$

$$\begin{aligned} \left. \frac{\partial V_{out}}{\partial r} \right|_R &= \left. -\frac{V_A R}{r^2} - \frac{2V_0 R^2}{r^3} \cos \theta \right|_R \\ &= -\frac{V_A}{R} - \frac{2V_0}{R} \cos \theta \end{aligned}$$

$$\left. \frac{\partial V_{in}}{\partial r} \right|_R = \frac{V_0}{R} \cos \theta$$

$$\begin{aligned} \sigma &= -\epsilon_0 \Delta \left. \frac{\partial V}{\partial r} \right|_R \\ &= \epsilon_0 \left(\frac{V_A}{R} + \frac{2V_0}{R} \cos \theta + \frac{V_0}{R} \cos \theta \right) \end{aligned}$$

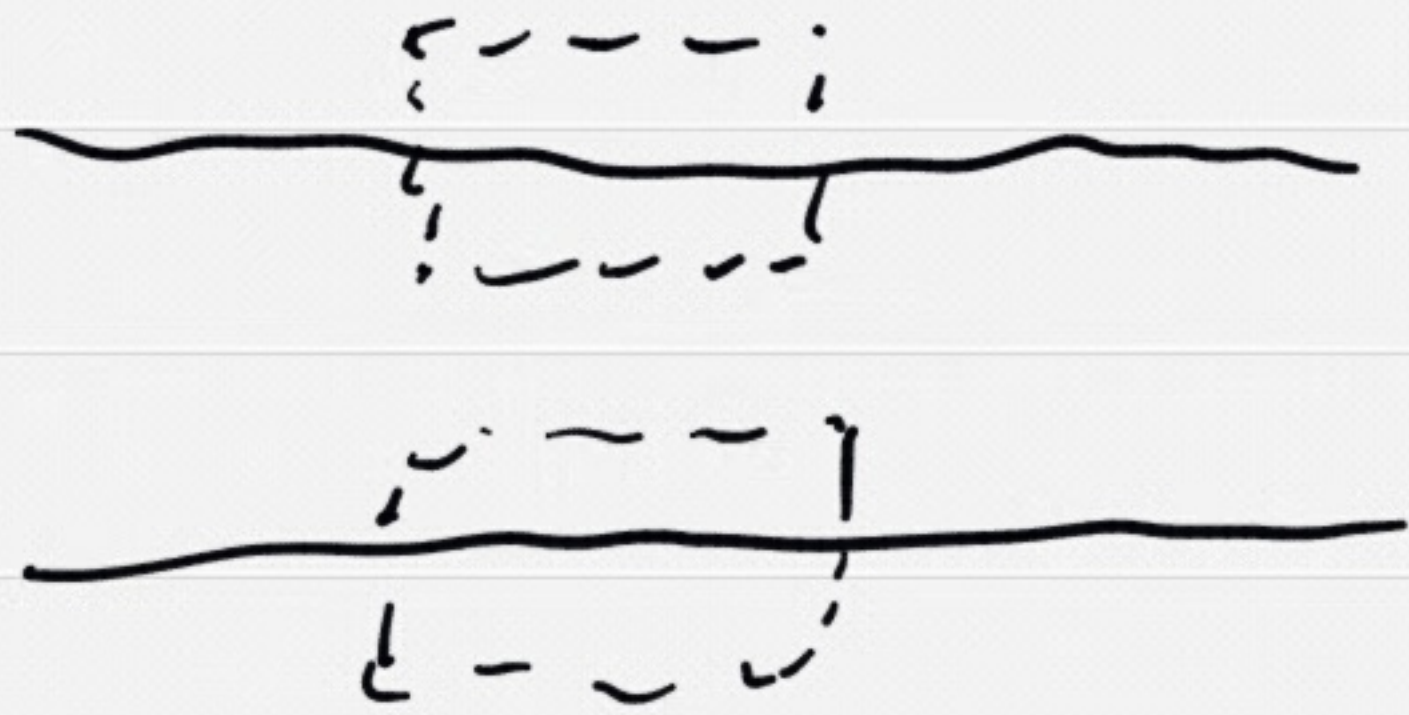
$$= \frac{\epsilon_0}{R} (V_A + 3V_0 \cos \theta)$$

4a. perp. continuous \Rightarrow (D)

b. perp. continuous \Rightarrow (B)

5. a. \vec{P} uniform $\Rightarrow \rho_t = 0$
 $\sigma_s = \vec{P} \cdot \hat{n} =$

- + ρ on top
- ρ on bottom



$$\oint \vec{E}_{top} \cdot d\vec{a} = 2 E_{top} A = \rho A / \epsilon_0$$

$$\Rightarrow E_{top} = \frac{\rho}{2\epsilon_0} \hat{n}$$

similarly $E_{bottom} = -\frac{\rho}{2\epsilon_0} \hat{n}$

$E_{above} = 0$
 $E_{in\ between} = \rho / \epsilon_0$ downward
 $E_{below} = 0$

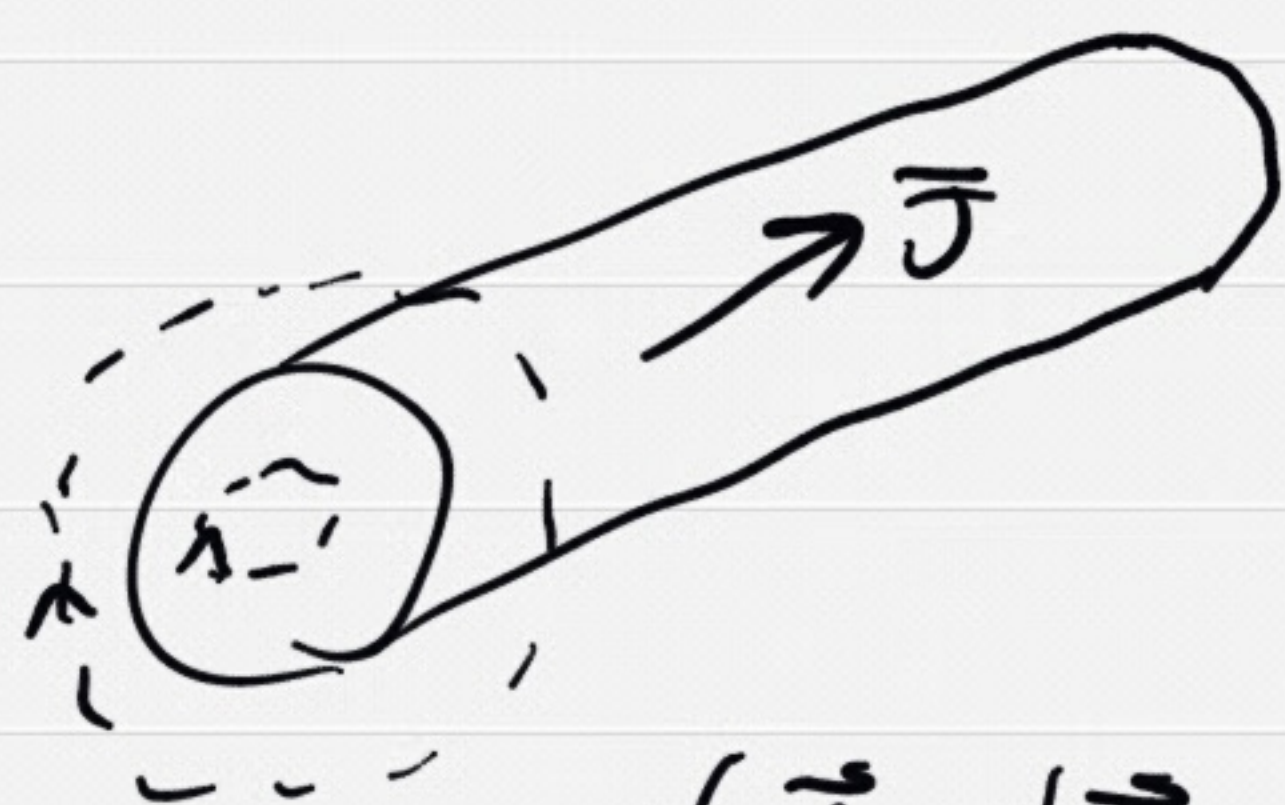
b. $D = \epsilon_0 \vec{E} + \vec{P}$

$D_{above} = 0$
 $D_{in\ between} = 0$
 $D_{below} = 0$

No free charge, so D continuous

$$6. \quad \mu = i \cdot \pi R^2 - i \pi R^2 \\ = 0$$

$$7. \quad \vec{J} = \frac{K}{s} \hat{z}$$



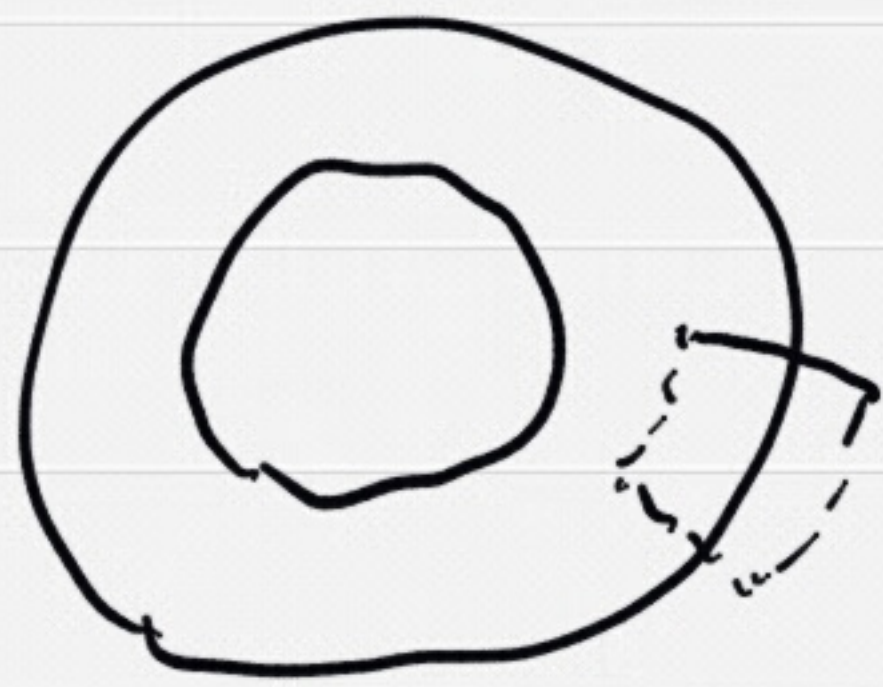
$$\oint \vec{B} \cdot d\vec{\ell} = \oint B_{\phi} \cdot 2\pi s \\ = \mu_0 I_{enc} \\ = \mu_0 \int \vec{J} \cdot d\vec{a} \\ = \mu_0 \int \frac{K}{s} \cdot 2\pi s \, ds \\ = \mu_0 \int 2\pi K \, ds \\ = \mu_0 \cdot 2\pi K s$$

$$\Rightarrow \vec{B}(s < R) = \mu_0 K \hat{\phi}$$

$$\vec{B}(s > R) = \frac{\mu_0 K R}{s} \hat{\phi}$$

$$\text{check } \nabla \times \vec{B} = \frac{\mu_0 K}{s} \hat{z} \quad s < R \\ = 0 \quad s > R //$$

8. a.



$$\oint \vec{H} \cdot d\vec{l} = H \cdot L$$
$$= I_{enc}$$
$$= NI \cdot \frac{L}{2\pi s}$$

$$\Rightarrow \vec{H} = \frac{NI}{2\pi s} \hat{\phi}$$

$$b. \vec{M} = \chi_m \vec{H} = \chi_m \frac{NI}{2\pi s} \hat{\phi}$$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$
$$= (1 + \chi_m) \frac{\mu_0 NI}{2\pi s} \hat{\phi}$$

$$c. \vec{J}_b = \nabla \times \vec{M}$$
$$= \frac{1}{s} \frac{\partial}{\partial s} (sM_{\phi}) \hat{z}$$
$$= 0$$

$$\vec{K}_b = \vec{M} \times \hat{n}$$
$$= -\chi_m \frac{NI}{2\pi b} \hat{z} \quad \text{outer}$$
$$= \chi_m \frac{NI}{2\pi s} \hat{s} \quad \text{top}$$
$$= \chi_m \frac{NI}{2\pi a} \hat{z} \quad \text{inner}$$
$$= -\chi_m \frac{NI}{2\pi s} \hat{s} \quad \text{bottom}$$
$$= \chi_m \vec{K}_{free}$$